Wed Jan 01 15:53:50 PST 2014 SAM 2b December 31, 2013 Video

			OF BY SECENTIAL STREET		
$\triangleright$	0:00	Governor Mode Stop	Governor switched to mode Stop, Servo to minimum		
D	0:06	Calibration Finished	At each Coldstart, the sensor and RC Values are calibrated to the actual seen values. If the calibration is finished, this message confirms the storage of data into the internal non volatile calibration memory		
4	0:16	Good Health Message (10sec)	This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.		
*	0:26	Good Health Message (10sec)	This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.		
*	0:36	Good Health Message (10sec)	This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.		
4	0:46	Good Health Message (10sec)	This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.		
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_	2:36	Good Health Message (10sec)	This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.		
_ ▷	2:44	Governor ON	Governor switched to mode ON		
D	2:49	Governor is at Low Throttle Limit	There is a defined low limit, that the Governor will not fall below. Ith this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.		
<b>D</b>	Throttle Limit Message is issued. Th		There is a defined low limit, that the Governor will not fall below. Ith this Limit is reached, this Info Message is issued. The Message is issued once for each touch of the limit. If the limit is touched, it means that your headspeed will be higher than programmed.		
<b>&gt;</b>	2:50	Governor input contains glitches  The Input signal of the Governor does not switch safely. It produces some additional slopes on and off state.			
D	2:53	Raised Vibration Level	There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and chis is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repediatly very often, check the heli for vibration sources.		
D	3:02	Bank 2 Loaded	Bank 2 was loaded from the non volatile memory. This can be triggered my manual bankswitch from the userinterface as well as in flight if bank switch is programmed to the aux channel.		
D	3:02	Raised Vibration Level	There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and chis is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repedidtly very often, check the heli for vibration sources.		
$\triangleright$	3:02	Governor ON	Governor switched to mode ON		
×		Extreme Vibration Level	Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations		
×	3:21	Extreme Vibration Level	Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations		
×	3:31	Extreme Vibration Level	Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations		
×	3:41	Extreme Vibration Level	Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations		

Page: 16

2:12 Re-Comp 11/4

2:50 Pre-Comp 0/0

	×	3:50	Extreme Vibration	Vibrations are extreme. That means, that the measurement signal is much lower than the signal level
			Level	of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations
	×	4:00	Extreme Vibration Level	Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations
	D	4:07	Bank 0 Loaded	Bank 0 was loaded from the non volatile memory. This can be triggered my manual backswitch from the userinterface as well as in flight if bank switch is programmed to the aux channel. On Startup the Bank 0 is loaded by default.
	$\triangleright$	4:07	Governor ON	Governor switched to mode ON
	D	4:10	Raised Vibration Level	There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and chis is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repediatly very often, check the heli for vibration sources.
	Δ	4:19	High Vibration Level	The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additinally slow drifts that happen may be caused by vibrations.
×	×	4:29	Extreme Vibration Level	Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations
	Δ	4:38	High Vibration Level	The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additinally slow drifts that happen may be caused by vibrations.
	<u>∧</u> T		The Cyclic Ring is active value 70 intentionally	If the agility of a Heli is set to the possibilities of the mechanic and aerodynamic limits, this did not happen. However in 3D Flying the agility cannot set high enough to fullfill the pilots needs. So this limiter is in action dependant on the flwon actions. If it is active very often, there is a potential problem with the mechanics. Using lighter blades will help increasing the natural agility preventing hitting the cyclic ring all the time.
<b>×</b>	X	4:48	Extreme Vibration Level	Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations
	D	4:50	Bank 2 Loaded	Bank 2 was loaded from the non volatile memory. This can be triggered my manual bankswitch from the userinterface as well as in flight if bank switch is programmed to the aux channel.
	$\triangleright$	4:50	Governor ON	Governor switched to mode ON
×	×	4:58	Extreme Vibration Level	Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations
	Δ	5:07	High Vibration Level	The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additinally slow drifts that happen may be caused by vibrations.
	×	5:17	Extreme Vibration Level	Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations
	×	5:27	Extreme Vibration Level	Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations
	D	5:28	Bank 3 Loaded	Bank 3 was loaded from the non volatile memory. This can be triggered my manual bankswitch from the userinterface as well as in flight if bank switch is programmed to the aux channel.
)	D	5:28	Governor ON	Governor switched to mode ON
>	×	5:36	Extreme Vibration Level	Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations
	×	5:46	Extreme Vibration Level	Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations
	×	5:55	Extreme Vibration Level	Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations
	×	6:05	Extreme Vibration Level	Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations
	×	6:15	Extreme Vibration Level	Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations
	×	6:24	Extreme Vibration Level	Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations
	×	6:34	Extreme Vibration Level	Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations
	×	6:43	Extreme Vibration Level	Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations
	Δ	6:53	High Vibration Level	The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additinally slow drifts that happen may be caused by vibrations.
	X	7:03	Extreme Vibration Level	Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations

Page: 17

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	×	7:12	Extreme Vibration Level	Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations
	Δ	7:22	High Vibration Level	The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additinally slow drifts that happen may be caused by vibrations.
	×	7:32	Extreme Vibration Level	Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations
(-12)	×	7:41	Extreme Vibration Level	Vibrations are extreme. That means, that the measurement signal is much lower than the signal level of the vibrations. No usable flying is possible with this level. Everything has to be checked and extended tests are needed to isolate and eliminate the source of vibrations
5: 13 3	<b>∆</b> W	7:51 /ドエ f	High Vibration Level	The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additinally slow drifts that happen may be caused by vibrations.
5:21	_		Bank 2 Loaded	Bank 2 was loaded from the non volatile memory. This can be triggered my manual bankswitch from the userinterface as well as in flight if bank switch is programmed to the aux channel.
Re-Comp	$\triangleright$	7:56	Governor ON	Governor switched to mode ON
11/4			High Vibration Level	The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additinally slow drifts that happen may be caused by vibrations.
Whip	D	8:10	Raised Vibration Level	There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and chis is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repediatly very often, check the heli for vibration sources.
worse	Δ	8:20	High Vibration Level	The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additinally slow drifts that happen may be caused by vibrations.
	1	8:30	Good Health Message (10sec)	This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.
	Δ	8:39	High Vibration Level	The control loop suffers from a high vibration level, that starts to render the sensors blind. Save flying is possible, but the stability will be degraded. Additinally slow drifts that happen may be caused by vibrations.
STOP	$\triangleright$	8:42	Governor Mode Stop	Governor switched to mode Stop, Servo to minimum
امادا	D		Raised Vibration Level	There was detected a raised level of Vibration. Since the vibration detector has to decide which signal is vibration and chis is the intended measurement signal, this can happen sometimes on hard 3d moves. It shall not happen all the time. If this error is reported repediatly very often, check the heli for vibration sources.
	1	8:59	Good Health Message (10sec)	This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.
	1	9:09	Good Health Message (10sec)	This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.
	1	9:19	Good Health Message (10sec)	This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.
	4	0:00	Coldstart	A Coldstart is done on the beginning of each switch on time. A Coldstart can happen only, if the VBar Units is disconnected from power for more than 5 Seconds.
	1	0:00	Reset Reason: Power On	This happens if power is applied to the VBar unit. Usually this is ok, but it shall never happen in operational mode. So if a reset happens during flight, this points to a power problem. During flight the power on reset results in a warmstart. If a coldstart happens during flight, the power loss was more than 5 Seconds
	D	0:00	Bank 0 Loaded	Bank 0 was loaded from the non volatile memory. This can be triggered my manual backswitch from the userinterface as well as in flight if bank switch is programmed to the aux channel. On Startup the Bank 0 is loaded by default.
	$\triangleright$	<b>ø</b> :00	Governor Mode Stop	Governor switched to mode Stop, Servo to minimum
	D	0:06	Calibration Finished	At each Colestart, the sensor and RC Values are calibrated to the actual seen values. If the calibration is finished, this message confirms the storage of data into the internal non volatile calibration phemory
	~	0:16	Good Health Message (10sec)	This Message describes the good health state. That means, that the VBar unit does not see any error or Into Message in the last 10 Seconds.
	-	0:26	Good Health Message (10sec)	This Message describes the good health state. That means, that the VBar unit goes not see any error or Info Message in the last 10 Seconds.
	1	0:36	Good Health Message (10sec)	This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.
	1	0:46	Good Health Message (10sec)	This Message describes the good health state. That means that the VBar unit does not see any error or Info Message in the last 10 Seconds.
	1	0:56	Good Health Message (10sec)	This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.
	1	1:06	Good Health Message (10sec)	This Message describes the good health state. That means, that the VBar unit does not see any error or Info Message in the last 10 Seconds.